A LOOK AT INTEL’S NEW NEHALEM ARCHITECTURE: THE BLOOMFIELD AND LYNNFIELD FAMILIES AND THE NEW TURBO BOOST TECHNOLOGY

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1. Introduction

Nehalem is the codename for the Intel processor microarchitecture successor to the Core microarchitecture. The first processor released with the Nehalem architecture is the desktop Core i7, which was released in November 2008.

Nehalem processors use the same 45 nm manufacturing methods as Penryn. A working system with two Nehalem processors was shown at Intel Developer Forum Fall 2007, and a large number of Nehalem systems were shown at Computex in June 2008.

The microarchitecture is named after the Nehalem Native American nation in Oregon. At that stage it was supposed to be the latest evolution of the NetBurst microarchitecture. Since the abandonment of NetBurst, the codename has been recycled and refers to a completely different project, although Nehalem still has some things in common with NetBurst. Nehalem-based microprocessors utilize higher clock speeds and are more energy-efficient than Penryn microprocessors. Hyper-Threading is reintroduced along with an L3 Cache missing from most Core-based microprocessors.

Nehalem is the “Tock” in Intel’s “Tick Tock” model, the “Tick” being the Penryn. "Tick-Tock" is a model adopted by Intel since 2007 to follow every microarchitectural change with shrinking of the process technology. Every "tick" is a shrinking of process technology of the previous microarchitecture and every "tock" is a new microarchitecture. Every year, there is expected to be one tick or tock.

2. Characteristics

The main characteristics of the Nehalem microarchitecture are:

- 45 nm manufacturing process
- 4 cores
- HyperThreading (some models)
- Intel Turbo Boost Technology
- A new point-to-point processor interconnect, the Intel QuickPath Interconnect, in high-end models, replacing the legacy front side bus
- Integrated memory controller supporting two or three memory channels
- 731 (Bloomfield) and 774 (Lynnfield) million transistors
- Integration of PCI Express and Direct Media Interface into the processor in mid-range models, replacing the northbridge

3. Families

The two processor families based on the Nehalem microarchitecture are Bloomfield (released in November 2008, Core i7 9xx series) and Lynnfield (September 2009, Core i7 8xx series and Core i5 750). The processor form the two families are quite different from each other, but the Lynnfield family can be seen as an evolution of Bloomfield. The main differences between the two are: socket (LGA 1366 for Bloomfield and LGA 1156 for Lynnfield), memory controller (3 channels for Bloomfield and 2
channels for Lynnfield, although the latter supports higher memory speeds than the first), PCI Express channels (36 for Bloomfield and 16 for Lynnfield).

Intel's Bloomfield Platform (X58 + LGA-1366):

Intel's Lynnfield Platform (P55 + LGA-1156):

<table>
<thead>
<tr>
<th>Processor</th>
<th>Clock Speed</th>
<th>Cores/Threads</th>
<th>Maxi Freq</th>
<th>Single Core</th>
<th>Turbo</th>
<th>TDP</th>
<th>Price</th>
</tr>
</thead>
<tbody>
<tr>
<td>Intel Core i7-975 Extreme</td>
<td>3.33GHz</td>
<td>4 / 8</td>
<td>3.60GHz</td>
<td></td>
<td></td>
<td>130W</td>
<td>$999</td>
</tr>
<tr>
<td>Intel Core i7 965 Extreme</td>
<td>3.20GHz</td>
<td>4 / 8</td>
<td>3.46GHz</td>
<td></td>
<td></td>
<td>130W</td>
<td>$999</td>
</tr>
<tr>
<td>Intel Core i7 940</td>
<td>2.93GHz</td>
<td>4 / 8</td>
<td>3.20GHz</td>
<td></td>
<td></td>
<td>130W</td>
<td>$562</td>
</tr>
</tbody>
</table>
Intel Core i7 920  2.66GHz  4 / 8  2.93GHz  130W  $284
Intel Core i7 870  2.93GHz  4 / 8  3.60GHz  95W  $562
Intel Core i7 860  2.80GHz  4 / 8  3.46GHz  95W  $284
Intel Core i5 750  2.66GHz  4 / 4  3.20GHz  95W  $196

4. Technologies

HyperThreading

Intel decided to reintroduce the HyperThreading technology, which means that every core can run two threads at the same time. This translates into 8 virtual processors seen by the operating system. HyperThreading is Intel’s proprietary SMT (simultaneous multithreading) technology and it has not been present on an Intel processor since the Pentium 4s in 2006.

QuickPath Interconnect

The QuickPath Interconnect (QuickPath, QPI) is a point-to-point processor interconnect developed by Intel to compete with HyperTransport (used by AMD). It replaces the Front Side Bus (FSB) for Desktop, Xeon, and Itanium platforms.

The QPI is an element of a system architecture that Intel calls the QuickPath architecture that implements what Intel calls QuickPath technology. In its simplest form on a single-processor motherboard, a single QPI is used to connect the processor to the IO Hub. In more complex instances of the architecture, separate QPI link pairs connect one or more processors and one or more IO hubs or routing hubs in a network on the motherboard, allowing all of the components to access other components via the network. As with HyperTransport, the QuickPath Architecture assumes that the processors will have integrated memory controllers, and enables a non-uniform memory architecture (NUMA).

Each QPI comprises two 20-lane point-to-point data links, one in each direction (full duplex), with a separate clock pair in each direction, for a total of 42 signals. Each signal is a differential pair, so the total number of pins is 84. The 20 data lanes are divided onto four "quadrants" of 5 lanes each. The basic unit of transfer is the 80-bit "flit," which is transferred in two clock cycles (four 20 bit transfers, two per clock.) The 80-bit "flit" has 8 bits for error detection, 8 bits for "link-layer header," and 64 bits for "data." QPI bandwidths are advertised by computing the transfer of 64 bits (8 bytes) of data every two clock cycles in each direction.

Although the initial implementations use single four-quadrant links, the QPI specification permits other implementations. Each quadrant can be used independently. On high-reliability servers, a QPI link can operate in a degraded mode. If one or more of the 20+1 signals fails, the interface will operate using 10+1 or even 5+1 remaining signals, even reassigning the clock to a data signal if the clock fails.

The initial Nehalem implementation uses a full four-quadrant interface to achieve 25.6 GB/s, which provides exactly double the theoretical bandwidth of Intel's 1600 MHz FSB used in the X48 chipset.
Turbo Boost

In a nutshell, Turbo Boost is overclocking. Actually it is real-time self overclocking done by the processor itself. It is yet another very smart technology that Intel developed to squeeze as much performance from the processor as possible.

In order to see how it works we have to understand TDP. The thermal design power (TDP), sometimes called thermal design point, represents the maximum amount of power the cooling system in a computer is required to dissipate. For example, a laptop's CPU cooling system may be designed for a 20 watt TDP, which means that it can dissipate up to 20 watts of heat without exceeding the maximum junction temperature for the computer chip. It can do this using an active cooling method such as a fan or any of the three passive cooling methods, convection, thermal radiation or conduction. Typically, a combination of methods are used. The TDP is typically not the most power the chip could ever draw, such as by a power virus, but rather the maximum power that it would draw when running real applications. This ensures the computer will be able to handle essentially all applications without exceeding its thermal envelope, or requiring a cooling system for the maximum theoretical power, which would cost more and achieve no benefit.

So we see that there is so much power a CPU can utilize before it becomes inefficient. The limit is somewhere around 140 W. The question is how to make a CPU run faster if we can’t use more power to increase frequency? The obvious solution was to make multi-core CPUs. Here’s an illustration of the concept:

<table>
<thead>
<tr>
<th></th>
<th>Single Core</th>
<th>Dual Core</th>
<th>Quad Core</th>
<th>Hex Core</th>
</tr>
</thead>
<tbody>
<tr>
<td>TDP</td>
<td>95W</td>
<td>47.5W</td>
<td>23.75W</td>
<td>15.8W</td>
</tr>
<tr>
<td>Tradeoff</td>
<td>Cores GHz</td>
<td>Cores GHz</td>
<td>Cores GHz</td>
<td>Cores GHz</td>
</tr>
</tbody>
</table>

If all cores are used then a lower clocked multi-core CPU is faster than a higher clocked single core CPU. But what happens when not all cores are used? And this happens a lot. Well, when let’s say just one core is used we can clearly see that the multi core CPU is slower then single core one because it has lower clock speed. This creates a dilemma: do you buy a single core, high clock speed CPU or a multi core lower clock speed one? The dilemma would disappear if the multi core CPU could use the extra power gained from the cores that are not running to overclock itself, making itself faster. That would be a smart CPU and that smart CPU is a Nehalem CPU.

But still, there is a problem: even cores that are not in use (idle) do use some amount of power. This limits the degree of “self-overclock” a CPU can achieve, not to mention that the extra used power is waste and, for mobile devices such as laptops, it’s a big concern. The solution to this is to turn off cores when they are not in use and turn them on when needed. Sounds simple, but it’s actually not. This is because transistors are used to turn off the cores. Transistors act like light switches, but because their size gets smaller and smaller (45 nm to date) we have power leakage between them even when they are supposed to be off. So, a core that is supposed to be turned off still draws power. Intel’s answer to this was the...
Power Gate Transistor (PGT). The PGT is a special kind of transistor that has almost zero leakage. This technology helps the Nehalem CPUs use the TDP gained from idle cores to power running cores, effectively overclocking them. This is what Turbo Boost is all about.

Turbo Boost was first implemented in Bloomfield, with some results (about 5% gain in performance, depending on the application running) and then it evolved with Lynnfield to about 17% increase in performance.

<table>
<thead>
<tr>
<th>Max Speed</th>
<th>Stock</th>
<th>4 Cores Active</th>
<th>3 Cores Active</th>
<th>2 Cores Active</th>
<th>1 Core Active</th>
</tr>
</thead>
<tbody>
<tr>
<td>Intel Core i7 870</td>
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</tr>
<tr>
<td>Intel Core i5 750</td>
<td>2.66GHz</td>
<td>2.80GHz</td>
<td>2.80GHz</td>
<td>3.20GHz</td>
<td>3.20GHz</td>
</tr>
</tbody>
</table>

If Intel had Turbo mode back when dual-cores first started shipping we would've never had the whole single vs. dual core debate. If you're running a single thread, this 774M transistor beast will turn off three of its cores and run its single active core at up to 3.6GHz. That's faster than the fastest Core 2 Duo on the market today.

The ultimate goal is to always deliver the best performance regardless of how threaded (or not) the workload is. Buying more cores shouldn't get you lower clock speeds, just more flexibility. The top end Lynnfield is like buying a 3.46GHz dual-core processor that can also run well threaded code at 2.93GHz.

Take this one step further and imagine what happens when you have a CPU/GPU on the same package or better yet, on the same die. Need more GPU power? Underclock the CPU cores, need more CPU power? Turn off half the GPU cores. It's always available, real-time-configurable processing power. That's the goal and Lynnfield is the first real step in that direction.

5. Conclusion

As awesome as it is, Turbo doesn't work 100% of the time, its usefulness varies on a number of factors including the instruction mix of active threads and processor cooling.

The actual instructions being executed by each core will determine the amount of current drawn and total TDP of the processor. For example, video encoding uses a lot of SSE instructions which in turn keep the SSE units busy on the chip; the front end remains idle and is clock gated, so power is saved there. The resulting power savings are translated into higher clock frequency. Intel tells us that video encoding should see the maximum improvement of two bins with all four cores active.

Floating point code stresses both the front end and back end of the pipe, here we should expect to see only a 133MHz increase from turbo mode if any at all. In short, you can't simply look at whether an app uses one, two or more threads. It's what the app does that matters.

There's also the issue of background threads running in the OS. Although your foreground app may only use a single thread, there are usually dozens (if not hundreds) of active threads on your system at any time. Just a few of those being scheduled on sleeping cores will wake them up and limit your max turbo frequency (Windows 7 is allegedly better at not doing this).

You can't really control the instruction mix of the apps you run or how well they're threaded, but this last point you can control: cooling. The sort-of trump all feature that you have to respect is Intel's thermal
throttling. If the CPU ever gets too hot, it will automatically reduce its clock speed in order to avoid damaging the processor; this includes a clock speed increase due to turbo mode.

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